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> # This example is example 1 in Chapter 5 of the book Modelling population dynamics: model
    # formulation, fitting and assessment using state-space methods
    # Press enter to activate each line of code (or use !!! button above to active all the code)
> restart;
> with(LinearAlgebra) :
> Dmat := proc(kappa, pars)
    local DD1, i, j;
    description "This procedure form the derivative matrix given a vector of exhaustive summary
        terms, kappa, and a vector of parameters, pars";
    with(LinearAlgebra) :
    DD1 := Matrix(1..Dimension(pars), 1..Dimension(kappa)) :
    for i from 1 to Dimension(pars) do
        for j from 1 to Dimension(kappa) do
            DD1[i, j] := diff(kappa[j], pars[i])
        end do
    end do;
    DD1;
    end proc:
> PLUR := proc(D1)
    local pp, ll, u1, r1, DetU;
    description "This procedure finds a PLUR or turing factorisation of the matrix D1." :
    (pp, ll, u1, r1) := LUDecomposition( D1, output = ['P','L','UI','R'] ) :
    DetU := Determinant(u1);
    {DetU=0, {P=pp, L=ll, U=u1, R=r1}} :
    end proc:
> Formnum := proc(D1)
    local results, j, numpars, D1rand :

    description "This procedure finds the rank and alpha for the hybrid-symbolic-numeric
        method";
    results := Matrix(5, 2) :
    for j from 1 to 5 do
        numpars := seq( indets(D1)[i] = evalf( ( rand( ) / 10000000000000 ) , i = 1 .. nops(indets(D1)) ) ) :
        D1rand := eval(D1, {numpars});
        results[j, 1] := Rank( D1rand);
        results[j, 2] := NullSpace( Transpose(D1rand) ) :
    end do:
    results :
    end proc:
> # forming the vector kappa which consists of the mean terms
> kappa := <n·p1·(1 - ψ·p2), n·(1 - p1)·p2, n·p1·ψ·p2, n - n·p1·(1 - ψ·p2) - n·(1 - p1)·p2
    - n·p1·ψ·p2>;

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$$\kappa := \begin{bmatrix} n p_1 (1 - \psi p_2) \\ n (1 - p_1) p_2 \\ n p_1 \psi p_2 \\ n - n p_1 (1 - \psi p_2) - n (1 - p_1) p_2 - n p_1 \psi p_2 \end{bmatrix}$$

> #The vector of parameters:

> $pars := \langle \psi, p_1, p_2 \rangle;$

$$pars := \begin{bmatrix} \psi \\ p_1 \\ p_2 \end{bmatrix}$$

> #Using the procedure Dmat to find the derivative matrix:

> $D1 := simplify(Dmat(kappa, pars));$

$$D1 := \begin{bmatrix} -n p_1 p_2 & 0 & n p_1 p_2 & 0 \\ -n (-1 + \psi p_2) & -n p_2 & n \psi p_2 & -n + n p_2 \\ -n p_1 \psi & -n (-1 + p_1) & n p_1 \psi & n (-1 + p_1) \end{bmatrix}$$

> #Finding the rank of the derivative matrix and the deficiency. A deficiency of greater than zero means the model is parameter redundant.

> $r := Rank(D1); d := Dimension(pars) - r;$

$$r := 3$$

$$d := 0$$

> # Using a PLUR decomposition to find any points where the model is not full rank.

> $PLURresults := PLUR(D1);$

$$PLURresults := \begin{bmatrix} -n^3 p_1 p_2 (-1 + p_1) = 0 \end{bmatrix},$$

$$\left\{ L = \begin{bmatrix} 1 & 0 & 0 \\ \frac{-1 + \psi p_2}{p_1 p_2} & 1 & 0 \\ \frac{\psi}{p_2} & \frac{-1 + p_1}{p_2} & 1 \end{bmatrix}, P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, R = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}, U \right.$$

$$= \begin{bmatrix} -n p_1 p_2 & 0 & n p_1 p_2 \\ 0 & -n p_2 & n \\ 0 & 0 & -\frac{(-1 + p_1) n}{p_2} \end{bmatrix}$$

> #The model will be parameter redundant for any solutions of $-n^3 p_1 p_2 (-1 + p_1) = 0$ for which P, L, R and U are defined.

So the model is parameter redundant if $n=0$ and if $p_1 = 1$.

#The model may be parameter redundant if p_1 or $p_2 = 0$, but L, U and R would be undefined in these cases so we need to check them separately.

> $\text{Rank}(\text{eval}(DI, p_1 = 0))$

2

> $\text{Rank}(\text{eval}(DI, p_2 = 0))$

2

> # As these are rank 2 rather than 3 the model is parameter redundant if p_1 or $p_2 = 0$

> # The hybrid-formal numerical method:

> $\text{Formnum}(DI)$

$$\begin{bmatrix} 3 & \{ \} \\ 3 & \{ \} \\ 3 & \{ \} \\ 3 & \{ \} \\ 3 & \{ \} \end{bmatrix}$$

> # This also shows the model has rank 3 (as the model is full rank $\alpha = \{ \}$)

> # A simpler exhaustive summary is (as long as n is not zero).

> $\kappa := \langle p_1 \cdot (1 - \Psi \cdot p_2), (1 - p_1) \cdot p_2, p_1 \cdot \Psi \cdot p_2 \rangle;$

$$\kappa := \begin{bmatrix} p_1 (1 - \Psi p_2) \\ (1 - p_1) p_2 \\ p_1 \Psi p_2 \end{bmatrix}$$

> #The vector of parameters:

> $\text{pars} := \langle \Psi, p_1, p_2 \rangle;$

$$pars := \begin{bmatrix} \Psi \\ p_1 \\ p_2 \end{bmatrix}$$

> #Using the procedure Dmat to find the derivative matrix:

> $D1 := Dmat(kappa, pars);$

$$D1 := \begin{bmatrix} -p_1 p_2 & 0 & p_1 p_2 \\ 1 - \Psi p_2 & -p_2 & \Psi p_2 \\ -p_1 \Psi & 1 - p_1 & p_1 \Psi \end{bmatrix}$$

> #Finding the rank of the derivative matrix and the deficiency. Note that we again find this model has rank 3.

> $r := Rank(D1); d := Dimension(pars) - r;$

$$r := 3$$

$$d := 0$$

> # A PLUR decomposition can be used with the new exhaustive summary and we get the same results, except for the result that the model is parameter redundant if $n=0$, as this is now an implicit assumption of the new exhaustive summary.

> $PLURresults := PLUR(D1);$

$$PLURresults := \left[\begin{array}{l} \\ \\ -p_1 p_2 (-1 + p_1) = 0, \\ \\ \end{array} \right]$$

$$\left\{ L = \begin{bmatrix} 1 & 0 & 0 \\ \frac{-1 + \Psi p_2}{p_1 p_2} & 1 & 0 \\ \frac{\Psi}{p_2} & \frac{-1 + p_1}{p_2} & 1 \end{bmatrix}, P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, U \right.$$

$$= \left[\begin{array}{l} \left[\begin{array}{l} -p_1 p_2 & 0 & p_1 p_2 \\ 0 & -p_2 & 1 \\ 0 & 0 & -\frac{-1 + p_1}{p_2} \end{array} \right] \\ \\ \end{array} \right]$$

> #The model will be parameter redundant for any solutions of $-p_1 p_2 (-1 + p_1) = 0$ for which P,

L, R and U are defined. So model is parameter redundant if $n = 0$ and if $p_1 = 1$. Model may be parameter redundant if p_1 or $p_2 = 0$, but L and R would be undefined in these cases so we need to check them separately.

```
> Rank(eval(DI, p1=0))
```

2

```
> Rank(eval(DI, p2=0))
```

2

```
> # As these are rank 2 rather than 3 the model is parameter redundant if p1 or p2 = 0
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> # The hybrid-formal numerical method also give a rank of 3 again:
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> Formnum(DI)
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[ 3 {} ]
[ 3 {} ]
[ 3 {} ]
[ 3 {} ]
[ 3 {} ]
```

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> # This also shows the model has rank 3 (as model is full rank alpha={})
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